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Weekly Report 1 (18 May 2006)

I have decided on a robot design. It will follow a line and avoid obstacles while balancing a cue ball on its large, flat top that will pan and tilt. I have also already ordered a board (Mavric-IIB), camera (CMUcam2), and two cue balls. I have many ideas in my head on ways to physically build a platform that can balance a ball. I will try to finalize these plans while I am waiting on my parts to arrive.